

Linear Algebra Sections 1594

Pg.68

31) Let $T: R^n \rightarrow R^m$ be a linear transformation, and let $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ be a linearly dependent set in R^n . Explain why the set $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ is linearly dependent.

In exercises 32-36, column vectors are written as rows, such as $\mathbf{x} = (x_1, x_2)$ and $T(\mathbf{x})$ is written as $T(x_1, x_2)$.

If $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly dependent, then there are x_1, x_2, x_3 , not all zero, such that $x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + x_3\mathbf{v}_3 = \mathbf{0}$. But then

$$T(x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + x_3\mathbf{v}_3) = T(\mathbf{0})$$

$$T(x_1\mathbf{v}_1) + T(x_2\mathbf{v}_2) + T(x_3\mathbf{v}_3) = \mathbf{0}$$

$$x_1T(\mathbf{v}_1) + x_2T(\mathbf{v}_2) + x_3T(\mathbf{v}_3) = \mathbf{0}$$

Since not all of x_1, x_2, x_3 are zero, this shows that $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ is linearly dependent.

33) Show that the transformation T defined by $T(x_1, x_2) = (x_1 - 2x_2, x_1 - 3, 2x_1 - 5x_2)$ is not linear.

$$T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 2x_2 \\ x_1 - 3 \\ 2x_1 - 5x_2 \end{bmatrix}$$

$$\text{Therefore, } T = \begin{bmatrix} 1 & -2 \\ 1 & 0 \\ 2 & -5 \end{bmatrix}$$

Is not linear because, it does not satisfy one of the properties. If T is linear then $T(0, 0) = (0, 0, 0)$

35) Let $T: R^3 \rightarrow R^3$ be the transformation that projects each vector $x = (x_1, x_2, x_3)$ onto the plane $x_2 = 0$, so $T(x) = (x_1, 0, x_3)$. Show that T is a linear transformation.

$$u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}, \quad v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

Prove that : $T(u+v) = T(u) + T(v)$

$$\begin{aligned} T(\mathbf{u} + \mathbf{v}) &= T \left(\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} + \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \right) = T \left(\begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix} \right) = \begin{bmatrix} u_1 + v_1 \\ 0 \\ u_3 + v_3 \end{bmatrix} = \\ &= \begin{bmatrix} u_1 \\ 0 \\ u_3 \end{bmatrix} + \begin{bmatrix} v_1 \\ 0 \\ v_3 \end{bmatrix} = T(\mathbf{u}) + T(\mathbf{v}). \end{aligned}$$

Prove that: $T(c\mathbf{u}) = cT(\mathbf{u})$

$$T(c\mathbf{u}) = T\left(c \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}\right) = T\left(\begin{bmatrix} cu_1 \\ cu_2 \\ cu_3 \end{bmatrix}\right) = \begin{bmatrix} cu_1 \\ 0 \\ cu_3 \end{bmatrix} = c \begin{bmatrix} u_1 \\ 0 \\ u_3 \end{bmatrix} = cT\left(\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}\right) = cT(\mathbf{u})$$

1)

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^4$, $T(\mathbf{e}_1) = (3, 1, 3, 1)$, and $T(\mathbf{e}_2) = (-5, 2, 0, 0)$,
where $\mathbf{e}_1 = (1, 0)$ and $\mathbf{e}_2 = (0, 1)$.

$$T(\mathbf{e}_1) = \begin{bmatrix} 3 \\ 1 \\ 3 \\ 1 \end{bmatrix} \quad T(\mathbf{e}_2) = \begin{bmatrix} -5 \\ 2 \\ 0 \\ 0 \end{bmatrix}$$

$$[T(\mathbf{e}_1) \ T(\mathbf{e}_2)] = \begin{bmatrix} 3 & -5 \\ 1 & 2 \\ 3 & 0 \\ 1 & 0 \end{bmatrix}$$

3)

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a vertical shear transformation that maps \mathbf{e}_1
into $\mathbf{e}_1 - 3\mathbf{e}_2$, but leaves \mathbf{e}_2 unchanged.

$$T = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}$$

$$T\mathbf{e}_1 = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \mathbf{e}_1 - 3\mathbf{e}_2$$

$$T\mathbf{e}_2 = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \mathbf{e}_1 + \mathbf{e}_2 = \mathbf{e}_2$$

5)

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ rotates points (about the origin) through $\pi/2$ radians (counterclockwise).

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ rotates points (about the origin) through $\frac{\pi}{2}$ radians (counterclockwise).

$$\begin{bmatrix} \cos\left(\frac{\pi}{2}\right) & -\sin\left(\frac{\pi}{2}\right) \\ \sin\left(\frac{\pi}{2}\right) & \cos\left(\frac{\pi}{2}\right) \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

7)

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ first rotates points through $-3\pi/4$ radians (clockwise) and then reflects points through the horizontal x_1 -axis. [Hint: $T(\mathbf{e}_1) = (-1/\sqrt{2}, 1/\sqrt{2})$.]

\mathbf{e}_1 goes to the point $(-1/\sqrt{2}, -1/\sqrt{2})$

\mathbf{e}_2 moves to the point $(1/\sqrt{2}, -1/\sqrt{2})$

the point $(1/\sqrt{2}, 1/\sqrt{2})$ after reflection.

$$T \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \quad \text{and} \quad T \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$
$$\begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

15)

In Exercises 15 and 16, fill in the missing entries of the matrix, assuming that the equation holds for all values of the variables.

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_1 - 4x_2 \\ x_1 - x_3 \\ -x_2 + 3x_3 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -4 & 0 \\ 1 & 0 & -1 \\ 0 & -1 & 3 \end{bmatrix}$$

17)

In Exercises 17–20, show that T is a linear transformation by finding a matrix that implements the mapping. Note that x_1, x_2, \dots are not vectors but are entries in vectors.

$$T(x_1, x_2, x_3, x_4) = (x_1 + 2x_2, 0, 2x_2 + x_4, x_2 - x_4)$$

$$\begin{aligned} T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}\right) &= \begin{bmatrix} x_1 + 2x_2 \\ 0 \\ 2x_2 + x_4 \\ x_2 - x_4 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 1 \\ 0 & 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \end{aligned}$$

So $T(\mathbf{x}) = A\mathbf{x}$ where

$$A = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 1 \\ 0 & 1 & 0 & -1 \end{bmatrix}$$

So T is a linear transform with standard matrix A .