## Resistance

Sunday, May 5, 2019

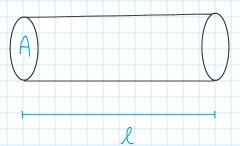
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In most material the induced emf is related to the current that flows in the circuit by Ohm's law, which is also valid in electrostatics

Where R is the resistance of the circuit. Notice however that, while

If the induced emf is due to a changing magnetic field, E is not a conservative field and we can't say that E is minus the gradient of the scalar potential.

The resistance of a straight conductor of constant section is



$$R = g \frac{L}{A}$$
  $[g] = \Omega m$ 

One can also define the conductivity as the inverse of the resistivity

$$O = \frac{1}{\rho}$$
  $O = CONDUCTIVITY$ 

T = OE Ohm's law can be written in general terms as

We can quickly check that for the case of a straight conductor of constant section one can recover the expression that we had above:

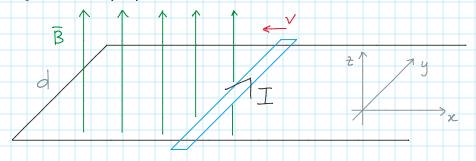
$$\mathcal{E} = \int \overline{E} \cdot d\overline{\ell} = \frac{1}{6} \int \overline{J} \cdot d\overline{\ell} = \frac{1}{6} \int \overline{A} \cdot n \cdot d\overline{\ell} = \frac{1}{6A} I \int d\ell = \overline{IL}$$

$$= \underbrace{\beta L}_{A} I = RI$$

$$A \underbrace{\uparrow}_{J}_{J}_{J} = \overline{A}$$

## Example: Loop of changing area in a constant magnetic field

Here we analyze again the example of a rectangular circuit with a that moves in a constant magnetic field perpendicular to the circuit.



The force acting on the blue moving bar is

$$F = Id \times B = IdB \hat{j} \times \hat{k} = IdB \hat{j}$$

From Newton's second law we have the position of the bar along the x axis must satisfy the relation

If there is no battery, the current I is due to the induced emf. Consequently the current will depend on the velocity of the bar along x.

$$\mathcal{E} = -\frac{d\phi}{dt} = -Bdv = -Bd\dot{x}$$

If we goes opposite to the x axis, the emf is positive, i.e. Tends to increase the current I = emf/R

$$I = \frac{\mathcal{E}}{R} = -\frac{Bd}{R}\dot{x}$$

By plugging this expression for the current in Newton's second law one finds.

$$m \ddot{x} = -\frac{Bd^{2}}{R} \dot{x} \qquad \frac{dv}{dt} = -\frac{Bd^{2}}{mR} v$$

$$\frac{dv}{v} = -\frac{Bd}{mR} dt \qquad \frac{dv}{mR} - \frac{Bd^{2}}{mR} \dot{x}$$

$$V = V_0 e^{-\frac{B^2 d^2}{mR}t}$$

No matter if the bar is moving initially to the left  $(v_0 < 0)$  or to the right  $(v_0 > 0)$  the bar will slow down and stop.

One can consider also the case in which there is a battery that provides an additional voltage V connected to the circuit. In that case

$$\mathcal{E} = V + \mathcal{E}_{induced} = V - Bd\dot{x}$$

$$T = \frac{V}{R} - \frac{Bd}{R}\dot{x}$$

$$m\ddot{x} = \frac{Bd}{R}\left(V - Bd\dot{x}\right) \rightarrow \frac{dv}{dt} = \frac{Bd}{mR}\left(V - Bdv\right)$$

$$V = \frac{B^{2}d^{2}}{R}t$$

$$V = \frac{Bd}{R}t$$

In order to fix the integration constant  $C_1$  one must impose that at t=0 the velocity is  $v_0$ .

$$V_{0} = \frac{V}{Bd} + C_{1} \longrightarrow C_{1} = V_{0} - \frac{V}{Bd}$$

$$V = \frac{V}{Bd} + e \frac{B^{2}d^{2}}{Bd} + e \frac{V_{0} - \frac{V}{Bd}}{Bd}$$

$$v = v_0 e^{\frac{2}{mR}t} + \frac{V}{Bd} \left(1 - e^{\frac{B^2d^2t}{mR}t}\right)$$

As t grows the exponentials become smaller and smaller. The velocity will reach a constant value V/(Bd).