

# Maxwell's equations in integral form

Saturday, September 1, 2018 8:45 AM

ME are often expressed in integral form

## Gauss' law for E

Integrate over a finite volume  $V$  bound by a closed surface  $\partial V$

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \rightarrow \int_V \nabla \cdot \vec{E} d^3r = \int_{\partial V} \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int_V \rho d^3r$$

GAUSS      FLUX  $\Phi_E(\partial V, t)$       TOTAL CHARGE  $Q$

$$\Phi_E(\partial V, t) = \frac{Q}{\epsilon_0}$$

The flux of  $E$  through the surface of  $V$  is proportional to  $Q$

## Gauss' law for B

$$\nabla \cdot \vec{B} = 0 \rightarrow \int_V \nabla \cdot \vec{B} d^3r = \int_{\partial V} \vec{B} \cdot d\vec{s} = 0 \rightarrow \Phi_B = 0$$

$\Phi_B(\partial V, t)$

The flux of  $B$  over a closed surface is zero, magnetic field lines are loops (closed lines)

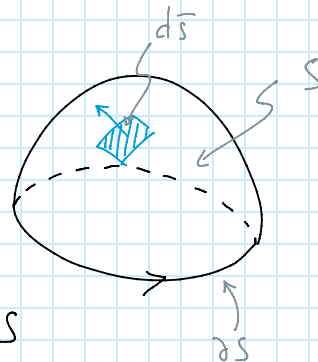
## Ampere-Maxwell's law

$$\nabla \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} + \mu_0 \vec{j}$$

Integrate over a surface  $S$  bound by a closed line  $\partial S$

$$\int_S (\nabla \times \vec{B}) \cdot d\vec{s} = \oint_{\partial S} \vec{B} \cdot d\vec{l} = \mu_0 \int_S d\vec{s} \cdot \left( \frac{\partial \vec{E}}{\partial t} \epsilon_0 + \vec{j} \right)$$

STOKES      CURRENT THROUGH THE SURFACE  $S$   
 $I(s, t)$



$$\oint_{\partial S} \vec{B} \cdot d\vec{\ell} = \mu_0 I$$

$I$  is the total current through the surface  $S$ . Notice that part of  $I$  comes from the Maxwell's displacement current  $\epsilon_0 \frac{\partial \vec{E}}{\partial t}$

Faraday's induction law

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

As for the Ampere Maxwell's case, integrate over a surface  $S$  bound by a closed line  $\partial S$

$$\int_S (\nabla \times \vec{E}) \cdot d\vec{s} = \oint_{\partial S} \vec{E} \cdot d\vec{\ell} = - \int_S \left( \frac{\partial}{\partial t} \vec{B} \right) \cdot d\vec{s} \quad (\text{I})$$

If the surface  $S$  does not change in time, one can exchange integration and time derivative to find

$$\underbrace{\oint_{\partial S} \vec{E} \cdot d\vec{\ell}}_{\mathcal{E} \text{ ELECTROMOTIVE FORCE (emf)}} = - \frac{d}{dt} \underbrace{\int_S \vec{B} \cdot d\vec{s}}_{\Phi_B(s,t)} \longrightarrow \mathcal{E} = - \frac{d}{dt} \Phi_B$$

The result remains valid also if  $S$  changes in time, but one needs to be careful with vector calculus and with the definition of e.m.f.

Let's start by considering the following theorem valid for a vector  $B$  (proof in Zangwill 1.4.5)

$$\frac{d}{dt} \int_{S(t)} \vec{B} \cdot d\vec{s} = \int_{S(t)} d\vec{s} \cdot \left\{ \frac{\partial \vec{B}}{\partial t} + \vec{v}_c (\nabla \cdot \vec{B}) - \nabla \times (\vec{v}_c \times \vec{B}) \right\}$$

In the equation above  $\vec{v}_c$  is the velocity of a given differential element  $d\vec{s}$  of the surface.

If we identify the vector  $B$  with the magnetic field, the relation above simplifies because the divergence of  $B$  is zero.

$$\frac{d}{dt} \int_{S(t)} \vec{B} \cdot d\vec{s} = \int_{S(t)} d\vec{s} \cdot \frac{\partial \vec{B}}{\partial t} - \int_{S(t)} \nabla \times (\vec{v}_c \times \vec{B}) \cdot d\vec{s}$$

$$\frac{d}{dt} \int_{S(t)} \bar{\mathbf{B}} \cdot d\bar{\mathbf{s}} = \int_{S(t)} d\bar{\mathbf{s}} \cdot \frac{\partial \bar{\mathbf{B}}}{\partial t} - \oint_{\partial S(t)} (\bar{\mathbf{v}}_c \times \bar{\mathbf{B}}) \cdot d\bar{\mathbf{l}}$$

$$\hookrightarrow \int_{S(t)} d\bar{\mathbf{s}} \cdot \frac{\partial \bar{\mathbf{B}}}{\partial t} = \frac{d}{dt} \int_{S(t)} \bar{\mathbf{B}} \cdot d\bar{\mathbf{s}} + \oint_{\partial S(t)} (\bar{\mathbf{v}}_c \times \bar{\mathbf{B}}) \cdot d\bar{\mathbf{l}} \quad (\text{II})$$

Now replace (II) in (I)

$$\oint_{\partial S(t)} \bar{\mathbf{E}} \cdot d\bar{\mathbf{l}} = - \frac{d}{dt} \int_{S(t)} \bar{\mathbf{B}} \cdot d\bar{\mathbf{s}} - \oint_{\partial S(t)} (\bar{\mathbf{v}}_c \times \bar{\mathbf{B}}) \cdot d\bar{\mathbf{l}}$$

$$\hookrightarrow \oint_{\partial S(t)} (\bar{\mathbf{E}} + \bar{\mathbf{v}}_c \times \bar{\mathbf{B}}) \cdot d\bar{\mathbf{l}} = - \frac{d}{dt} \underbrace{\int_{S(t)} \bar{\mathbf{B}} \cdot d\bar{\mathbf{s}}}_{\phi_B} \quad (\text{III})$$

If  $\partial S$  is assumed to coincide with a loop of conducting wire which can change shape in time,  $\bar{\mathbf{v}}_c$  is the local velocity of the heavy ions which give the material mass and rigidity. Electrons carrying current in the wire move with respect to the ions with a drift velocity

$$\underbrace{\bar{\mathbf{v}}_e(\bar{\mathbf{r}}, t)}_{e^- \text{ velocity}} \equiv \bar{\mathbf{v}}_c(\bar{\mathbf{r}}, t) + \underbrace{\bar{\mathbf{v}}_d(\bar{\mathbf{r}}, t)}_{\text{drift velocity}}$$

However the drift velocity is parallel to the line element  $d\bar{\mathbf{l}}$ , therefore

$$(\bar{\mathbf{v}}_d \times \bar{\mathbf{B}}) \cdot d\bar{\mathbf{l}} = 0$$

One can then replace the drift velocity with the electron velocity in (III)

$$\underbrace{\oint_{\partial S(t)} d\bar{\mathbf{l}} \cdot (\bar{\mathbf{E}} + \bar{\mathbf{v}}_e \times \bar{\mathbf{B}})}_{\text{FARADAY'S ELECTROMOTIVE FORCE}} = - \frac{d}{dt} \phi_B$$