

Euler Lagrange equation

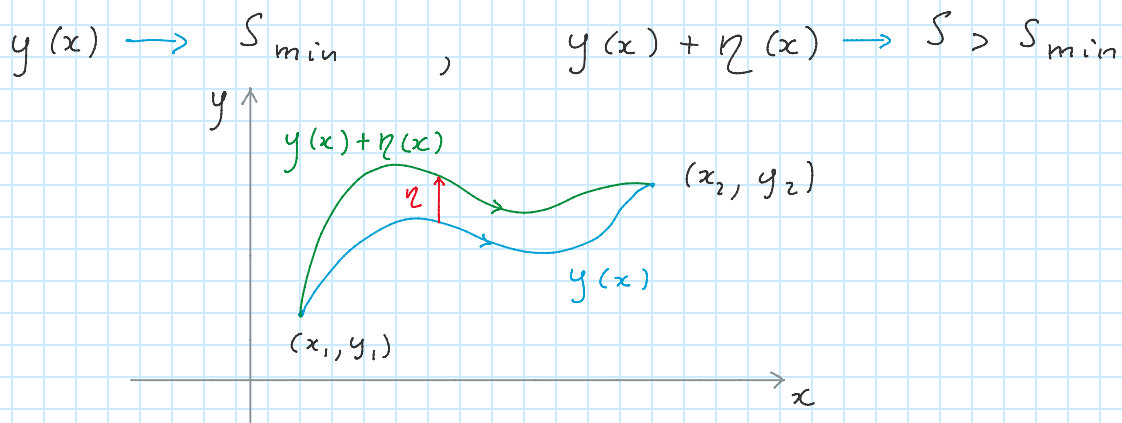
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Here we want to solve in general terms the problem of choosing a path that minimizes the integrals defined in the two examples discussed above, namely, what is the shortest distance between two points in a plane and what is the shortest time light will take to go from a given initial point to a given final point.

Both problems require to minimize an integral of the general form

$$S = \int_{x_1}^{x_2} f [y(x), y'(x), x] dx$$

As a first step and unavoidable step, we try to figure out for which paths $y(x)$ S has a stationary value. Let's suppose that a certain (unknown) $y(x)$ corresponds to the minimum value of S . If we deform slightly the path $y(x)$, then S will have a larger value than the one it has for the curve $y(x)$ that corresponds to the minimum.



The endpoints of the curve, and of the integral, are however fixed

$$\eta(x_1) = \eta(x_2) = 0$$

One can actually parameterize a family of curves that are "close" to $y(x)$ but do not coincide with $y(x)$ by introducing the parameter α

$$Y(x) \equiv y(x) + \alpha \eta(x)$$

If one inserts Y in the integral S , also the latter will depend on α

$$S(\alpha) \equiv \int_{x_1}^{x_2} f(Y, Y', x) dx$$
$$= \int_{x_1}^{x_2} f(y + \alpha \eta, y' + \alpha \eta', x) dx$$

S is now a regular function of α . Consequently, it will have a stationary point when its derivative vanishes

$$\left. \frac{dS}{d\alpha} \right|_{\alpha=0} = \int_{x_1}^{x_2} \frac{\partial f}{\partial \alpha} dx = \int_{x_1}^{x_2} \left(\eta \frac{\partial f}{\partial y} + \eta' \frac{\partial f}{\partial y'} \right) dx = 0$$

Now apply integration by parts to the second term in the round bracket

$$\int_{x_1}^{x_2} \left(\frac{d}{dx} \eta(x) \right) \frac{\partial f}{\partial y'} dx = \underbrace{\left[\eta(x) \frac{\partial f}{\partial y'} \right]_{x_1}^{x_2}}_{=0 \text{ since } \eta(x_1) = \eta(x_2) = 0} - \int_{x_1}^{x_2} \eta(x) \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) dx$$

Therefore

$$\left. \frac{dS}{d\alpha} \right|_{\alpha=0} = \int_{x_1}^{x_2} \left(\eta \frac{\partial f}{\partial y} - \eta \frac{d}{dx} \frac{\partial f}{\partial y'} \right) dx = 0$$
$$\hookrightarrow \int_{x_1}^{x_2} \eta(x) \left(\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} \right) dx = 0$$

Since we are dealing with continuous functions, and we are free to choose an arbitrary function η , the integral will be zero only if

$$\boxed{\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0}$$

EULER LAGRANGE
EQUATION

Let's consider again the last logical step. Can one have

$$\int_{x_1}^{x_2} \eta(x) F(x) dx = 0$$

for arbitrary η if F is not equal to zero? Remember the assumption that we are dealing with smooth continuous functions. If F is not zero for every x , we can choose a η that has the same sign of F in each point x . Therefore, the integrand will be positive in each point where F is different from zero. This implies that the integral will only receive positive contributions, so it cannot be zero. We reached a contradiction. Consequently our assumption that the integral is zero is incompatible with the assumption that F is not zero everywhere. Consequently

$$\int_{x_1}^{x_2} \eta(x) F(x) dx = 0 \quad \forall \eta \rightarrow F(x) = 0$$

Consequently, by requiring that $y(x)$ satisfies the Euler Lagrange equation we can find the solution of the problems which we are trying to solve. As a first application let's go back to the case of the problem of finding the shortest path between two points

$$L = \int_1^2 ds = \int_{x_1}^{x_2} \sqrt{1 + (y')^2} dx \rightarrow f(x) \equiv \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

$$\frac{\partial f}{\partial y} = 0 \quad \frac{\partial f}{\partial y'} = \frac{1}{2} \frac{2 y'}{\sqrt{1 + (y')^2}} = \frac{y'}{\sqrt{1 + (y')^2}}$$

$$\frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{d}{dx} \left(\frac{y'}{\sqrt{1 + (y')^2}} \right) = 0$$

$$\hookrightarrow y' = C \sqrt{1 + (y')^2} \rightarrow (y')^2 = C^2 (1 + (y')^2)$$

$$(y')^2 (1 - C^2) = C^2 \rightarrow (y')^2 = \frac{C^2}{1 - C^2}$$

$$\hookrightarrow y' = \textcircled{K} \leftarrow \text{constant}$$

$$y = kx + x_0$$

Impose the boundary conditions

$$y(x_1) = y_1 \rightarrow y_1 = kx_1 + x_0, \quad y(x_2) = y_2 \rightarrow y_2 = kx_2 + x_0$$

$$y_2 - y_1 = k(x_2 - x_1) \rightarrow k = \frac{y_2 - y_1}{x_2 - x_1}$$

$$y_1 = \frac{y_2 - y_1}{x_2 - x_1} x_1 + x_0 \rightarrow x_0 = \frac{y_1 x_2 - y_1 x_1 - y_2 x_1 + y_1 x_1}{x_2 - x_1}$$

$$x_0 = \frac{y_1 x_2 - y_2 x_1}{x_2 - x_1}$$

$$y = \frac{y_2 - y_1}{x_2 - x_1} x + \frac{y_1 x_2 - y_2 x_1}{x_2 - x_1}$$

Check

$$x \rightarrow x_2 \quad y = \frac{y_2 x_2 - y_1 x_2 + y_1 x_2 - y_2 x_1}{x_2 - x_1} = y_2 \quad \checkmark$$