

Spring pendulum

Saturday, October 31, 2020 9:12 AM

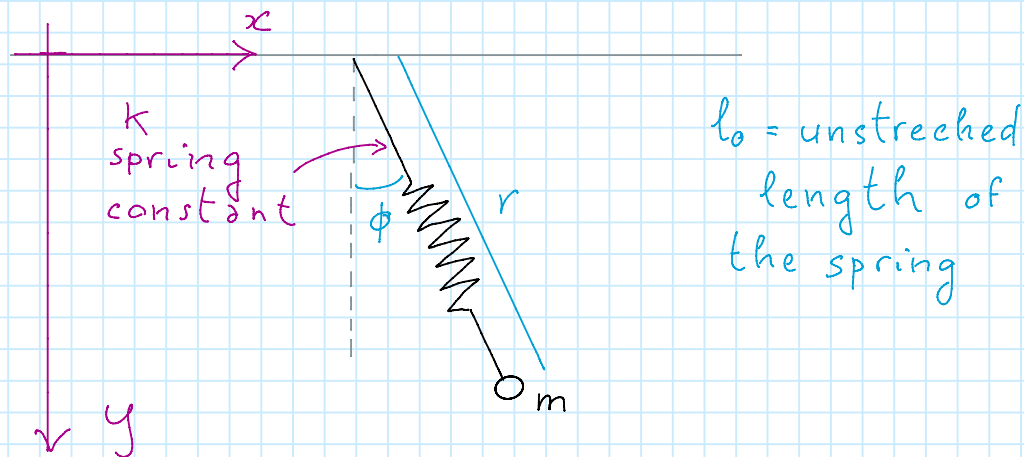
Problem 7.36 in Taylor

A pendulum is made of a massless spring that is suspended at one end from a fixed pivot O and has a mass m attached to the other end. The spring can stretch and compress but it cannot bend and the whole system is confined to a single vertical plane.

A) write down the Lagrangian of the pendulum, using as generalized coordinates the usual angle ϕ and the length r of the spring.

B) find the two Lagrange equations.

C) solve the equations in the case of small oscillations



$$\mathcal{L} = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\phi}^2) - \frac{k}{2} (r - l_0)^2 + mgr \cos \phi$$

r and ϕ are functions of t

$$\frac{\partial \mathcal{L}}{\partial r} = m r \dot{\phi}^2 - k(r - l_0) + mg \cos \phi$$

$$\frac{\partial \mathcal{L}}{\partial \dot{r}} = m \dot{r}$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}} - \frac{\partial \mathcal{L}}{\partial r} = m \ddot{r} - m r \dot{\phi}^2 + k(r - l_0) - mg \cos \phi = 0$$

$$m\ddot{r} - \underbrace{m r \dot{\phi}^2}_{\text{centripetal acceleration}} = - \underbrace{k(r - l_0)}_{\text{spring force}} - \underbrace{mg \cos \phi}_{\text{radial component of the weight}}$$

$$\frac{\partial \mathcal{L}}{\partial \phi} = -m g r \sin \phi$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\phi}} = m r^2 \dot{\phi}$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} - \frac{\partial \mathcal{L}}{\partial \phi} = 2 m r \dot{r} \dot{\phi} + m r^2 \ddot{\phi} + m g r \sin \phi = 0$$

$$\ddot{\phi} = - \underbrace{\frac{g}{r} \sin \phi}_{\text{tangential component of the weight}} - 2 \frac{\dot{r}}{r} \dot{\phi}$$

Small oscillations

set $r = l + \epsilon$ where l is the equilibrium length of the spring when the mass m is hanging

$$mg = k(l - l_0)$$

the equation for r can then be rewritten in terms of ϵ as follows

$$m \ddot{\epsilon} + m(l + \epsilon) \dot{\phi}^2 = -k(l - l_0) - k\epsilon + mg \cos \phi$$

Now assume that ϵ and ϕ are small quantities of the same order and neglect quadratic terms

$$m\ddot{\epsilon} = -k(l-l_0) - K\epsilon + mg = -K\epsilon$$

$$\ddot{\epsilon} = -\frac{K}{m}\epsilon$$

harmonic
oscillator
equation

$$\ddot{\phi} = -\frac{g}{r}\phi$$

harmonic
oscillator
equation