

Precession in an axially symmetric body.

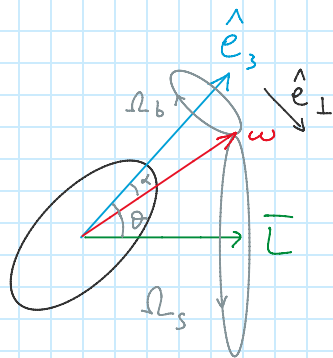
Sunday, December 8, 2019 4:23 PM

Taylor, problem 10.46

In the free precession of an axially symmetric body the vectors \hat{e}_3 , ω , and L stay on the same plane. Prove the relations

$$\Omega_s = \omega \frac{\sin \alpha}{\sin \vartheta} = \frac{L}{\lambda_1} = \omega \frac{\sqrt{\lambda_3^2 + (\lambda_1^2 - \lambda_3^2) \sin^2 \alpha}}{\lambda_1}$$

Solution



$\bar{\Omega}_b = -\Omega_b \hat{e}_3$ angular vel
of $\bar{\omega}$ w.r.t the
body frame

$\bar{\Omega}_s = \Omega_s \frac{\bar{L}}{L}$ angular velocity
of $\bar{\omega}$ w.r.t the
space frame

$\bar{\omega}$ angular velocity of
the body frame w.r.t
the space frame

Angular velocities add up like regular velocities

$$[\bar{\Omega}_s]_{ws} = [\bar{\Omega}_b]_{wb} + [\bar{\omega}]_{bs}$$

multiply the relation above by a unit vector
perpendicular to \hat{e}_3 (call it \hat{e}_\perp)

$$\hat{e}_\perp \cdot \bar{\Omega}_s = \hat{e}_\perp \cdot \bar{\Omega}_b + \hat{e}_\perp \cdot \bar{\omega}$$

$\hat{e}_\perp \cdot \hat{e}_3 = 0$

$$\hat{e}_\perp \cdot \bar{\omega} = \omega \cos\left(\frac{\pi}{2} - \alpha\right) = \omega \sin \alpha$$

$$\hat{e}_1 \cdot \bar{L} = L \cos\left(\frac{\pi}{2} - \theta\right) = L \sin\theta$$

$$\hat{e}_1 \cdot \bar{\Omega}_s = \Omega_s \sin\theta$$

$$\Omega_s \sin\theta = \omega \sin\alpha$$

$$\Omega_s = \omega \frac{\sin\alpha}{\sin\theta}$$

$$\Omega_s = \frac{\omega \sin\alpha}{\sin\theta} = \frac{\omega_1}{\sin\theta} = \frac{\omega_1}{L_1/L} = \frac{L}{\lambda_1} \quad \text{since } L_1 = \lambda_1 \omega_1$$

Finally

$$L^2 = \lambda_1^2 \omega_1^2 + \lambda_2^2 \omega_2^2 + \lambda_3^2 \omega_3^2$$

but $\lambda_1 = \lambda_2$

$$\omega_1 = \omega \sin\alpha \cos\varphi$$

$$\omega_2 = \omega \sin\alpha \sin\varphi$$

$$\omega_3 = \omega \cos\alpha$$

$$L^2 = (\lambda_1^2 \sin^2\alpha + \lambda_3^2 \cos^2\alpha) \omega^2$$

$$= (\lambda_1^2 \sin^2\alpha + \lambda_3^2 - \lambda_3^2 \sin^2\alpha) \omega^2$$

$$\Omega_s = \frac{L}{\lambda_1} = \omega \frac{\lambda_3^2 + (\lambda_1^2 - \lambda_3^2) \sin^2\alpha}{\lambda_1}$$